

MODE	1 RUN	2 WRT	3 PCL	4 Deg	5 Rad	6 Grd	7 Fix
8 Sci	9 Norm	+ COMP	- BASE-N	X SD1	÷ LR1	· Defrn	= CONT
SHIFT	4 o	5 r	6 g	X SD2	÷ LR2		
ALPHA	1 $\Sigma X^2$	2 $\Sigma X$	3 n	4 $\Sigma Y^2$	5 $\Sigma Y$	6 $\Sigma XY$	

<b>MODE</b>	<b>SHIFT</b>	<b>ALPHA</b>	<b>Cls</b> G ↔ T	Line Value	
Goto	Zoom Org	Factor	Plot	← REPLAY →	
<b>Prog</b>	<b>Graph</b>	<b>Range</b>	<b>Trace</b>	X ↔ Y	
:	<b>ENG</b>	Int $\sqrt{\quad}$	Frac $X^2$	$10^x$ <b>log</b>	$e^x$ <b>ln</b>
xnor k	Not xor m	Dec d p	Hex h n	Bin b P	Oct o f
X!	$X^{-1}$	<b>hyp</b>	$\sin^{-1}$ <b>sin</b>	$\cos^{-1}$ <b>cos</b>	$\tan^{-1}$ <b>tan</b>
A A	B B	C C	D D	E E	F F
d/c <b>a<sup>b</sup>/c</b>	<b>→</b>	(	)	Abs $X^y$	$\sqrt[3]{\quad}$ $x\sqrt{\quad}$
Neg G	Sci H	I	J	and CL K	or DT L
<b>7</b>	<b>8</b>	<b>9</b>	<b>DEL</b>	Mcl	OFF ON
A M	B N	r O			
lsz <b>4</b>	$\geq$ <b>5</b>	$\leq$ <b>6</b>	Zoom xf <b>X</b>	Zoom xf / f <b>÷</b>	
$\bar{Y}$ P	Yon Q	Yon -1 R	$\bar{X}$ S	$\bar{Y}$ T	
Dsz <b>1</b>	$>$ <b>2</b>	$<$ <b>3</b>	Pol( <b>+</b>	Rec( <b>-</b>	
$\bar{X}$ U	Xon V	Xon -1 W	X	Y	
Rnd <b>0</b>	Ran# <b>.</b>	pi <b>EXP</b>	(-) <b>ANS</b>	<b>EXE</b>	
Z	I	I	SPACE		

Courtesy of H Hayes